

Semidefinite programming hierarchies for polynomial programs

CMU 10-725 Optimization
Fall 2012

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(yes, this is going to be handwritten.)

There's life beyond convex optimization.

(Now you tell us...)

Example 1: Sparse estimation

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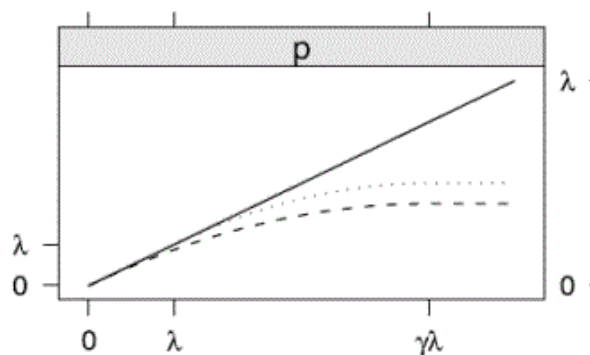
Statistically, not an ideal estimator. [Zha12]

- if $\min_j |w_j^*|$ is large, $\|w - w^*\|$ is suboptimal by a factor of $\sqrt{\ln(n)}$ ("Lasso bias")
- under " l_2 regularity conditions", w does not have the correct support (even asymptotically)

$$\text{MCP penalty: } \min_w \sum_{t=1}^T (y_t - \langle w, x_t \rangle)^2 + \lambda \sum_{j=1}^n \rho(|w_j|)$$

$$\rho(|w_j|) = \begin{cases} \lambda |w_j| - w_j^2 / 2\gamma & |w_j| \leq \lambda\gamma \\ \frac{1}{2} \gamma \lambda^2 & \text{otherwise} \end{cases}$$

LASSO ——— MCP - - - - - SCAD ······



[Bre11]

Example 2: Linear Classification

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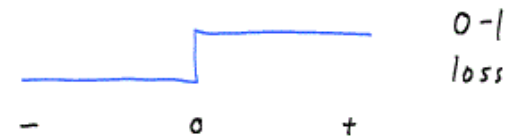
Goal: $\min_w \mathbb{E}_{(x,y) \sim \mathcal{D}} [\mathbb{1}(\langle w, x_t \rangle \neq y_t)]$



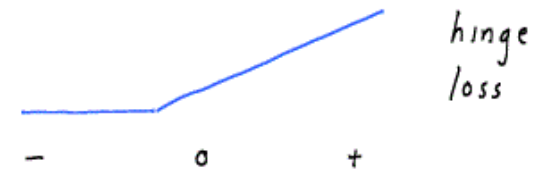
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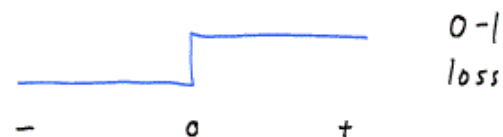
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- need margin or exponential amount of data [Sha10]

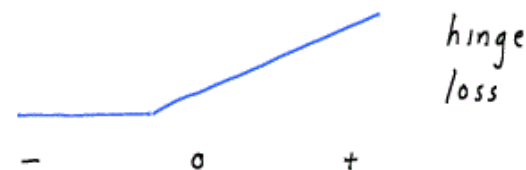
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Classical learning theory supports regularized ERM:

$$\min_w \sum_{t=1}^T \mathbb{1}[\text{sgn}(\langle w, x_t \rangle) \neq y_t] \quad \text{s.t.} \quad \|w\|_2^2 \leq B$$

Polynomial optimization

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$$\min. p(x) \quad \text{s.t.} \quad g_1(x) \geq 0, \dots, g_m(x) \geq 0$$

where p and g_i are polynomials

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- Very general.
- Not always well-defined.

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$$\|w\|_2 \geq \epsilon$$

polynomials as vectors (in basis of monomials)

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$$= \langle (5, 2, 3, -1, 0, 4.7), \vec{p} \text{ (will drop } \vec{\text{)}} \rangle$$
$$(x_1^0x_2^0, x_1^1x_2^0, x_1^0x_2^1, x_1^1x_2^1, x_1^2x_2^0, x_1^0x_2^2)$$

↪ $\phi_D(x)$ is the vector of monomials of x up to degree D .
of dimension $\binom{n+D}{D}$ (here, $D=2$)

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$$= \sum_{\substack{\alpha = (\alpha_1, \dots, \alpha_D) \\ \text{s.t. } |\alpha| \leq D}} \vec{p}_\alpha X^\alpha$$

where $X^\alpha = x_1^{\alpha_1} \cdots x_n^{\alpha_n}$
(here, $n=2$)

semidefinite programming

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$$\min_y \langle c, y \rangle \quad \text{s.t.} \quad \sum_x y_x A_x^i \geq 0 \quad \forall i, \quad Cy = b$$

linear objective PSD cone constraints affine constraints

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linear
objective

PSD cone
constraints

affine
constraints

one PSD constraint

infinitely many linear constraints

$$P \geq 0 \quad \Leftrightarrow \quad v^T P v \geq 0 \quad \forall v$$

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Encoding the constraints

PSD cone is pointed:

$$P \geq 0 \wedge -P \geq 0 \Rightarrow P = 0$$

semidefinite programming

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linear objective *PSD cone constraints* *affine constraints*

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Given $P \geq 0, P \neq 0$

$$g_i(x) \geq 0 \iff g_i(x) P \geq 0$$

O K

$$0 \preceq \phi_D(x) \phi_D(x)^T$$

$$\begin{aligned} 0 &\preceq \phi_D(x) \phi_D(x)^T \\ &= [\phi_D(x)_\alpha \quad \phi_D(x)_\beta]_{\alpha, \beta} \end{aligned}$$

$$\begin{aligned} 0 &\preceq \phi_D(x) \phi_D(x)^T \\ &= [\phi_D(x)_\alpha \phi_D(x)_\beta]_{\alpha, \beta} \\ &= [x^\alpha x^\beta]_{\alpha, \beta} \end{aligned}$$

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$$= [x^\alpha x^\beta]_{\alpha, \beta} \quad x^\alpha x^\beta = x^\gamma \quad \text{for} \quad \alpha + \beta = \gamma$$

$$\begin{aligned}
O &\preceq \phi_D(x) \phi_D(x)^T \\
&= [\phi_D(x)_\alpha \phi_D(x)_\beta]_{\alpha, \beta} \\
&= [x^\alpha x^\beta]_{\alpha, \beta} \\
&= \sum_{\gamma} x^\gamma I_\gamma
\end{aligned}$$

		β					
		0	1	2	3	4	5
α	0				1		
	1			1			
	2			1			
	3	1					
	4						

$n=1$
 $\gamma=3$

$x^\alpha x^\beta = x^\gamma$ for $\alpha + \beta = \gamma$.
 I_γ is matrix with 1s in these cells.

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$$\underbrace{\hspace{10em}}_{A_{\gamma}^i}$$

The relaxation

$$\min_x \sum_{\gamma} p_{\gamma} x^{\gamma}$$

s.t.
:

$$\sum_{\gamma} x^{\gamma} A_{\gamma}^i \geq 0 \quad \forall 1 \leq i \leq m$$

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linearize x^{α} to y_{α}

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Moment relaxation of order D

$$V_{pop} = \min_x p(x) \quad \text{s.t.} \quad 1 = g_0(x) \geq 0, \quad g_1(x) \geq 0, \quad \dots, \quad g_m(x) \geq 0$$

$$V_{mom}^D = \min_y \sum_{|\gamma| \leq d} p_\gamma y_\gamma \quad \text{s.t.} \quad \sum_{|\gamma| \leq D} y_\gamma A_\gamma^i \geq 0 \quad \forall 0 \leq i \leq m$$

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• Under some conditions, for big enough D , it is tight!

$$V_{mom}^{D^*} = V_{pop}$$

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$$\begin{aligned} s_j(x)^2 &= \langle s, \phi(x) \rangle \langle s, \phi(x) \rangle \\ &= (s_j^T \phi(x))^T (s_j^T \phi(x)) \end{aligned}$$

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Conversely, every $Q \succeq 0$ ^{of appropriate size} defines a sum of squares:

$$Q = S^T S = \begin{bmatrix} | & & | \\ s_1 & \cdots & s_k \\ | & & | \end{bmatrix} \begin{bmatrix} \text{---} s_1 \text{---} \\ \vdots \\ \text{---} s_k \text{---} \end{bmatrix}$$

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$$\begin{aligned} \min_y \quad & \sum_{|\alpha| \leq d} p_\alpha y_\alpha & \text{s.t.} \quad & y_0 = 1 \\ & & & \sum_{|\alpha| \leq D} y_\alpha A_\alpha^i \geq 0 \quad \forall 0 \leq i \leq m \end{aligned}$$

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$$L_i y \geq 0$$

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$$g_i^T y y y^T = L_i y \geq 0$$

$$\begin{aligned} & g_i(x) \phi_b(x) \phi_b(x)^T \\ &= \left(\sum_\alpha g_\alpha^i x^\alpha \right) \left(\sum_\beta I_\beta x^\beta \right) \\ &= \sum_\alpha \sum_\beta g_\alpha^i I_\beta x^{\alpha+\beta} \\ &= \sum_\gamma x^\gamma \underbrace{\sum_{\alpha+\beta=\gamma} g_\alpha^i I_\beta}_{A_\gamma^i} \end{aligned}$$

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$$b = \begin{bmatrix} 1 \\ 0 \\ \vdots \end{bmatrix}, \quad \text{so} \quad \langle b, l \rangle = l_0 \quad \equiv \quad p(\cdot) - l_0$$

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$$K^* \quad K = K_0 + \dots + K_m = \left\{ \sum_{\bar{i}=0}^m R_{\bar{i}} : R_{\bar{i}} \in K_{\bar{i}} \right\}$$

\mathbb{R}^n x $\mathbb{R}^{\begin{pmatrix} n+D \\ D \end{pmatrix}}$ $\phi(x)$ 

$$q_i: \mathbb{R}^n \rightarrow \mathbb{R}$$

$$q_i(x) = \langle Q_i, L_i(\phi(x)) \rangle$$

$$\langle L_i^T Q, y \rangle \geq 0 \quad \forall y \in K_i^*$$

→ subset of K_i

$$\left(\mathbb{R}^{\begin{pmatrix} n+D \\ D \end{pmatrix}} \right)^2$$

$$L_i(\phi(x))$$

$$L_i(y)$$

$$L_i(K_i^*) \subseteq Z = Z^*$$

For $Q_i \in Z$

$$\langle Q_i, P \rangle \geq 0 \quad \forall P \in Z$$

$$\langle Q_i, P \rangle \geq 0 \quad \forall P \in L_i K_i^*$$

$$\langle Q_i, L_i y \rangle \geq 0 \quad \forall y \in K_i^*$$

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What is K_i^* ?

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$$= \{ \langle y, R \rangle \geq 0 \quad \forall R \in \underbrace{L_i^T Z}_{K_i} \}$$

A functional view of $R \in K_i = L_i^T Z$

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$$\begin{aligned} R(y) &= \langle y, R \rangle = \langle y, L_i^T Q \rangle \quad \text{for some } Q \geq 0 \\ &= \langle L_i y, Q \rangle \end{aligned}$$

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AKA the truncated quadratic module
 ↘ to degree D

The SDP hierarchies

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$$V_{\text{mom}}^D = \min. \langle p, y \rangle \quad \text{s.t.} \quad [Y_\alpha Y_\beta]_{|\alpha|, |\beta| \leq D} \geq 0$$
$$\sum_{|\gamma| \leq D} Y_\gamma A_\gamma^i \geq 0 \quad \forall 1 \leq i \leq m$$
$$Y_0 = 1$$

$$V_{\text{sos}}^D = \max_{l_0} l_0 \quad \text{s.t.} \quad p - l_0 = q_0 + \sum_{i=1}^m g_i q_i$$

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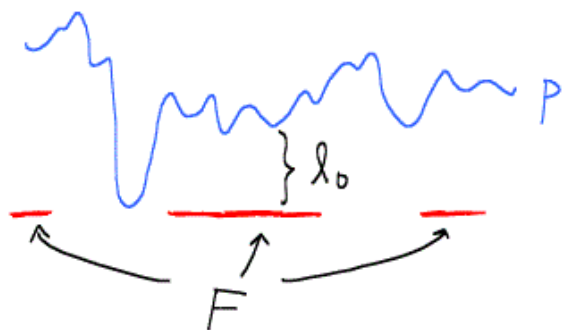
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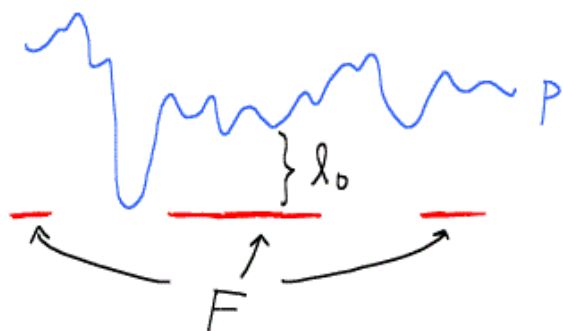
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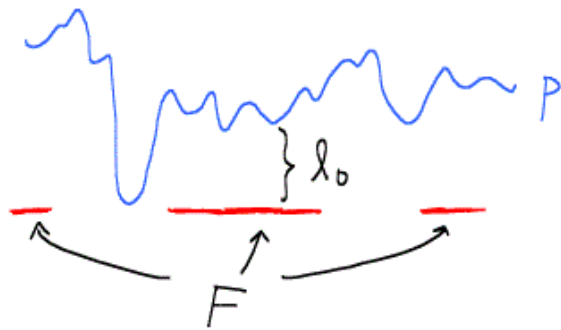
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⇒ $p - l_0$ has a certificate of nonnegativity (at round D)

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This is Putinar's Positivstellensatz, a specialization of a central result in algebraic geometry.

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- Sparsity

Go forth and optimize!